NAG Toolbox for MATLAB

f08tq

1 Purpose

f08tq computes all the eigenvalues and, optionally, all the eigenvectors of a complex generalized Hermitian-definite eigenproblem, of the form

$$Az = \lambda Bz$$
, $ABz = \lambda z$ or $BAz = \lambda z$,

where A and B are Hermitian, stored in packed format, and B is also positive-definite. If eigenvectors are desired, it uses a divide-and-conquer algorithm.

2 Syntax

3 Description

f08tq first performs a Cholesky factorization of the matrix B as $B = U^{H}U$, when **uplo** = 'U' or $B = LL^{H}$, when **uplo** = 'L'. The generalized problem is then reduced to a standard symmetric eigenvalue problem

$$Cx = \lambda x$$
,

which is solved for the eigenvalues and, optionally, the eigenvectors; the eigenvectors are then backtransformed to give the eigenvectors of the original problem.

For the problem $Az = \lambda Bz$, the eigenvectors are normalized so that the matrix of eigenvectors, z, satisfies

$$Z^{H}AZ = \Lambda$$
 and $Z^{H}BZ = I$,

where Λ is the diagonal matrix whose diagonal elements are the eigenvalues. For the problem $ABz = \lambda z$ we correspondingly have

$$Z^{-1}AZ^{-H} = \Lambda$$
 and $Z^{H}BZ = I$,

and for $BAz = \lambda z$ we have

$$Z^{H}AZ = \Lambda$$
 and $Z^{H}B^{-1}Z = I$.

4 References

Anderson E, Bai Z, Bischof C, Blackford S, Demmel J, Dongarra J J, Du Croz J J, Greenbaum A, Hammarling S, McKenney A and Sorensen D 1999 *LAPACK Users' Guide* (3rd Edition) SIAM, Philadelphia URL: http://www.netlib.org/lapack/lug

Golub G H and Van Loan C F 1996 Matrix Computations (3rd Edition) Johns Hopkins University Press, Baltimore

5 Parameters

5.1 Compulsory Input Parameters

1: itype – int32 scalar

Specifies the problem type to be solved.

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itype = 1

$$Az = \lambda Bz$$
.
itype = 2
 $ABz = \lambda z$.
itype = 3
 $BAz = \lambda z$.

2: **jobz – string**

If jobz = 'N', compute eigenvalues only.

If jobz = 'V', compute eigenvalues and eigenvectors.

Constraint: jobz = 'N' or 'V'.

3: **uplo – string**

If $\mathbf{uplo} = 'U'$, the upper triangles of A and B are stored.

If $\mathbf{uplo} = 'L'$, the lower triangles of A and B are stored.

Constraint: uplo = 'U' or 'L'.

4: n - int32 scalar

n, the order of the matrices A and B.

Constraint: $\mathbf{n} \geq 0$.

5: ap(*) – complex array

Note: the dimension of the array **ap** must be at least $\max(1, \mathbf{n} \times (\mathbf{n} + 1)/2)$.

The n by n Hermitian matrix A, packed by columns.

More precisely,

if **uplo** = 'U', the upper triangle of A must be stored with element A_{ij} in $\mathbf{ap}(i+j(j-1)/2)$ for $i \le j$;

if **uplo** = 'L', the lower triangle of A must be stored with element A_{ij} in $\mathbf{ap}(i+(2n-j)(j-1)/2)$ for $i \ge j$.

6: bp(*) – complex array

Note: the dimension of the array **bp** must be at least $\max(1, \mathbf{n} \times (\mathbf{n} + 1)/2)$.

The upper or lower triangle of the Hermitian matrix B, packed by columns.

More precisely,

if **uplo** = 'U', the upper triangle of B must be stored with element B_{ij} in **bp**(i+j(j-1)/2) for i < i:

if **uplo** = 'L', the lower triangle of B must be stored with element B_{ij} in **bp**(i + (2n - j)(j - 1)/2) for $i \ge j$.

5.2 Optional Input Parameters

None.

5.3 Input Parameters Omitted from the MATLAB Interface

ldz, work, lwork, rwork, lrwork, iwork, liwork

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5.4 Output Parameters

1: ap(*) - complex array

Note: the dimension of the array **ap** must be at least $\max(1, \mathbf{n} \times (\mathbf{n} + 1)/2)$.

The contents of ap are destroyed.

2: bp(*) - complex array

Note: the dimension of the array **bp** must be at least $\max(1, \mathbf{n} \times (\mathbf{n} + 1)/2)$.

The triangular factor U or L from the Cholesky factorization $B = U^H U$ or $B = L L^H$, in the same storage format as B.

3: $\mathbf{w}(*)$ – double array

Note: the dimension of the array w must be at least $max(1, \mathbf{n})$.

If info = 0, the eigenvalues in ascending order.

4: $\mathbf{z}(\mathbf{ldz},*) - \mathbf{complex} \text{ array}$

The first dimension, **ldz**, of the array **z** must satisfy

if
$$jobz = 'V'$$
, $ldz \ge max(1, n)$; $ldz \ge 1$ otherwise.

The second dimension of the array must be at least $max(1, \mathbf{n})$

If $\mathbf{jobz} = \mathbf{'V'}$, then if $\mathbf{info} = 0$, \mathbf{z} contains the matrix Z of eigenvectors. The eigenvectors are normalized as follows:

if **itype** = 1 or 2,
$$Z^HBZ = I$$
; if **itype** = 3, $Z^HB^{-1}Z = I$.

If iobz = 'N', z is not referenced.

5: info - int32 scalar

info = 0 unless the function detects an error (see Section 6).

6 Error Indicators and Warnings

Errors or warnings detected by the function:

$$info = -i$$

If info = -i, parameter i had an illegal value on entry. The parameters are numbered as follows:

1: itype, 2: jobz, 3: uplo, 4: n, 5: ap, 6: bp, 7: w, 8: z, 9: ldz, 10: work, 11: lwork, 12: rwork, 13: lrwork, 14: iwork, 15: liwork, 16: info.

It is possible that **info** refers to a parameter that is omitted from the MATLAB interface. This usually indicates that an error in one of the other input parameters has caused an incorrect value to be inferred.

info > 0

f07gr or f08gq returned an error code:

- \leq **n** if **info** = i, f08gq failed to converge; i off-diagonal elements of an intermediate tridiagonal form did not converge to zero;
- > **n** if **info** = **n** + i, for $1 \le i \le$ **n**, then the leading minor of order i of B is not positive-definite. The factorization of B could not be completed and no eigenvalues or eigenvectors were computed.

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7 Accuracy

If B is ill-conditioned with respect to inversion, then the error bounds for the computed eigenvalues and vectors may be large, although when the diagonal elements of B differ widely in magnitude the eigenvalues and eigenvectors may be less sensitive than the condition of B would suggest. See Section 4.10 of Anderson $et\ al.\ 1999$ for details of the error bounds.

The example program below illustrates the computation of approximate error bounds.

8 Further Comments

The total number of floating-point operations is proportional to n^3 .

The real analogue of this function is f08tc.

9 Example

```
itype = int32(2);
jobz = 'No vectors';
uplo = 'U':
n = int32(4);
ap = [complex(-7.36, +0);
     complex(0.77, -0.43);
complex(3.49, +0);
     complex(-0.64, -0.92);
     complex(2.19, +4.45);
     complex(0.12, +0);
      complex(3.01, -6.97);
     complex(1.9, +3.73);
     complex(2.88, -3.17);
complex(-2.54, +0)];
bp = [complex(3.23, +0);
     complex(1.51, -1.92);
     complex(3.58, +0);
     complex(1.9, +0.84);
     complex(-0.23, +1.11);
      complex(4.09, +0);
     complex(0.42, +2.5);
     complex(-1.18, +1.37);
     complex(2.33, -0.14);
complex(4.29, +0)];
[apOut, bpOut, w, z, info] = f08tq(itype, jobz, uplo, n, ap, bp)
apOut =
  -6.3313
   3.7915
  10.0314
   0.0159 + 0.7178i
  46.3757
 -27.6834
   0.6398 - 0.6015i
  -0.0228 + 0.2162i
 -15.5151
  -1.1075
bpOut =
   1.7972
   0.8402 - 1.0683i
   1.3164
   1.0572 + 0.4674i
  -0.4702 - 0.3131i
   1.5604
   0.2337 + 1.3910i
   0.0834 - 0.0368i
   0.9360 - 0.9900i
   0.6603
```

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```
w =
    -61.7321
    -6.6195
    0.0725
    43.1883
z =
    1.0e-53 *
    0.0000 + 0.0000i    0.0000 + 0.0000i    -0.3233
info =
    0
```

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